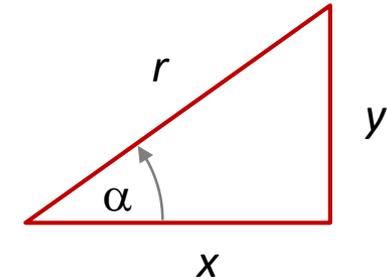


# Trigonometrische Relationen

$$\sin \alpha = \frac{y}{r} \quad \cos \alpha = \frac{x}{r} \quad \tan \alpha = \frac{y}{x} = \frac{\sin \alpha}{\cos \alpha}$$



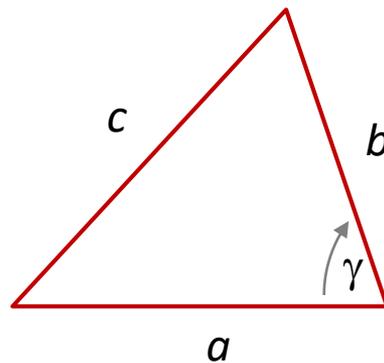
$$\sin^2 \alpha + \cos^2 \alpha = 1$$

$$\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \sin \beta \cos \alpha \quad \sin(2\alpha) = 2\sin \alpha \cos \alpha$$

$$\cos(\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta$$

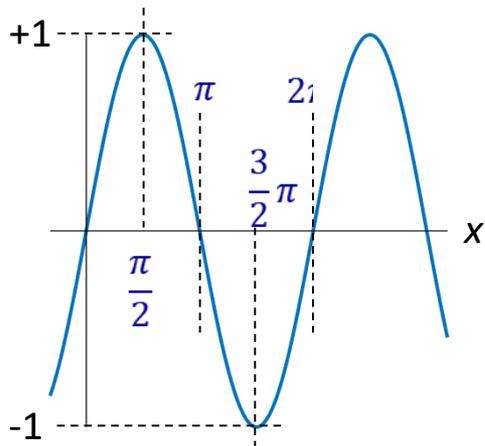
Kosinussatz

$$c^2 = a^2 + b^2 - 2ab \cos \gamma$$

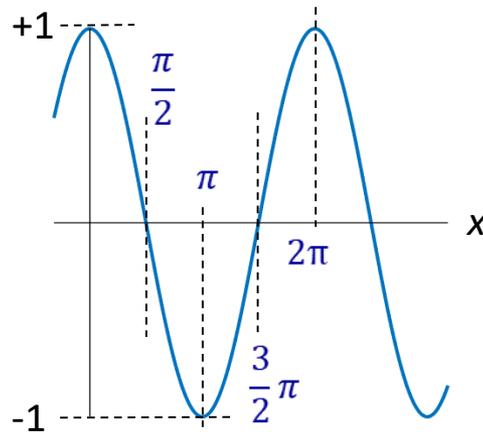


# Elementare Funktionen

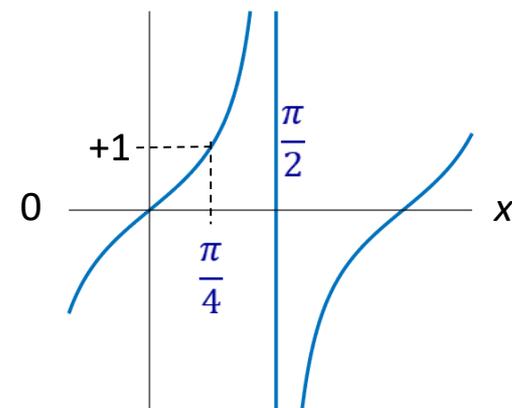
$y=\sin(x)$



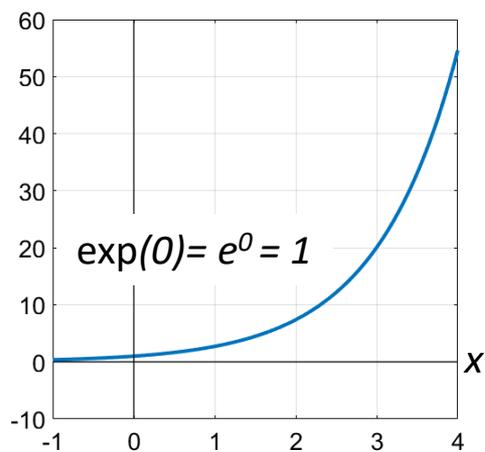
$y=\cos(x)$



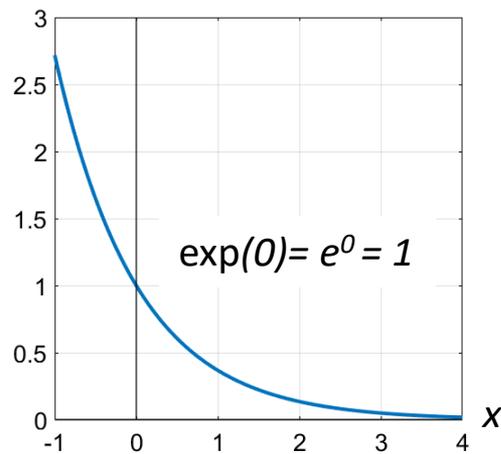
$y=\tan(x)$



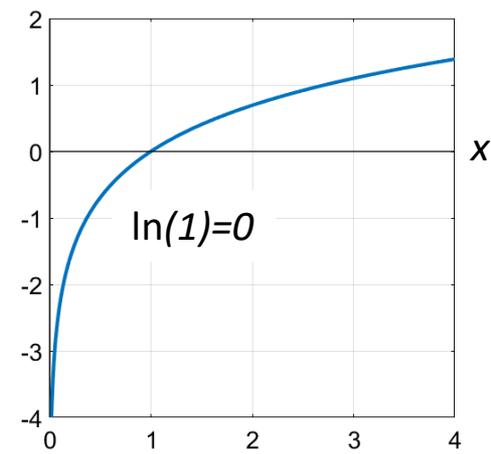
$y=\exp(x)=e^x$



$y=\exp(-x)=e^{-x}$



$y=\ln(x)$



# Ableitungen und Integrale

$f(x)$	$\frac{d}{dx}f(x)$	$\int f(x)dx$
$x^n$	$nx^{n-1}$	$\frac{1}{n+1}x^{n+1}$
$\frac{1}{x}$	$-\frac{1}{x^2}$	$\ln(x)$
$\sin(x)$	$\cos(x)$	$-\cos(x)$
$\cos(x)$	$-\sin(x)$	$\sin(x)$
$\tan(x)$	$\frac{1}{\cos^2 x}$	$-\ln(\cos(x))$
$\exp(x) = e^x$	$\exp(x) = e^x$	$\exp(x) = e^x$
$\ln(x)$	$\frac{1}{x}$	$x \ln(x) - x$

# Näherungen/Taylorreihen

$$(1+x)^n \approx 1 + nx + \frac{n(n-1)}{2}x^2$$

$$\frac{1}{1+x} \approx 1 - x$$

$$\sin(x) \approx x - \frac{1}{3}x^3$$

$$\cos(x) \approx 1 - \frac{1}{2}x^2$$

$$\tan(x) \approx x + \frac{1}{3}x^3$$

$$e^x \approx 1 + x + \frac{1}{2}x^2$$

$$\ln(1+x) \approx x - \frac{x^2}{2}$$

# Komplexe Zahlen

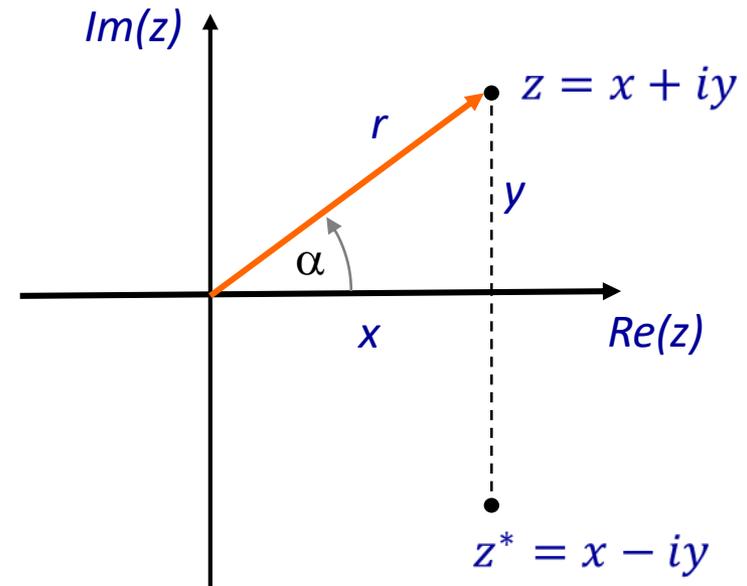
$$z = x + iy \quad i^2 = -1 \quad i = \sqrt{-1}$$

$$x = \operatorname{Re}(z)$$

$$y = \operatorname{Im}(z)$$

$$z = r e^{i\alpha} \quad r = \sqrt{x^2 + y^2}$$

$$\tan \alpha = \frac{y}{x} = \frac{\operatorname{Re}(z)}{\operatorname{Im}(z)}$$

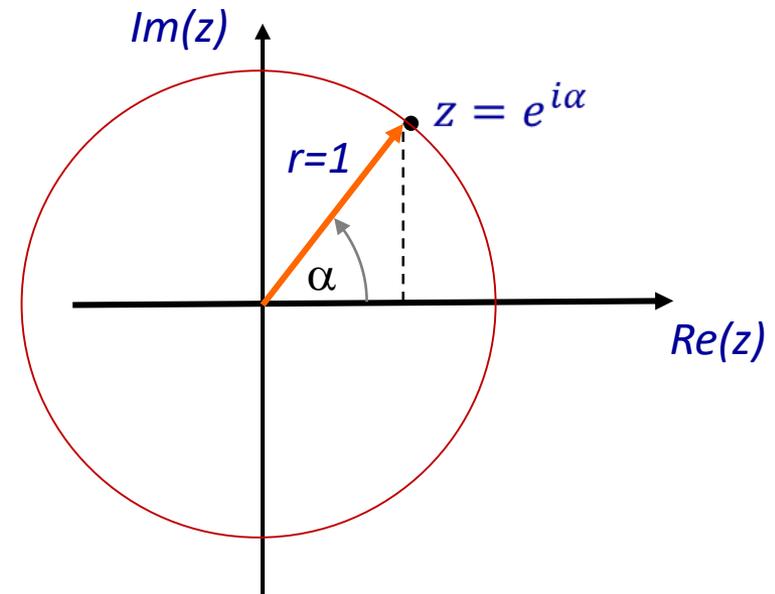


Einheitskreis

$$z = e^{i\alpha} = \cos \alpha + i \sin \alpha$$

$$\cos \alpha = \frac{1}{2} (e^{i\alpha} + e^{-i\alpha})$$

$$\sin \alpha = \frac{1}{2i} (e^{i\alpha} - e^{-i\alpha})$$

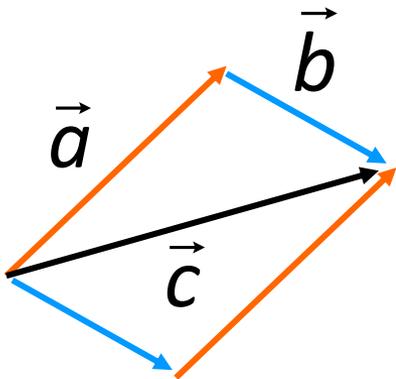
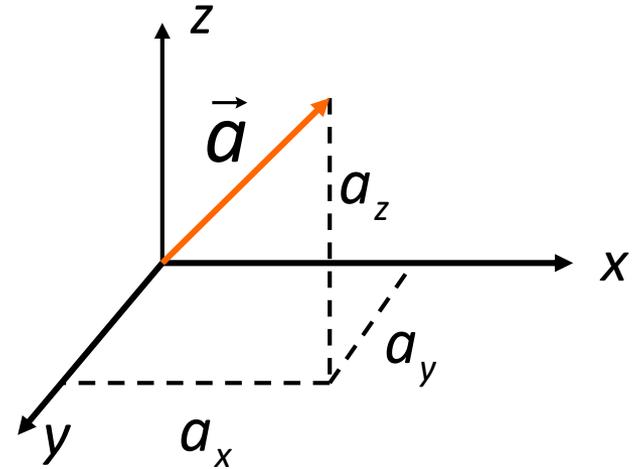


# Vektoren

**Skalare Größen:** Betrag mit Einheit

**Vektorielle Größen:** Richtung und Betrag mit Einheit

$$\vec{a} = \begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix}$$



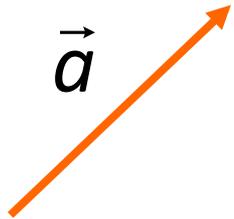
$$\vec{c} = \vec{a} + \vec{b}$$

$$\vec{c} = \vec{b} + \vec{a}$$

$$\vec{c} = \begin{pmatrix} a_x + b_x \\ a_y + b_y \\ a_z + b_z \end{pmatrix}$$

# Vektoren

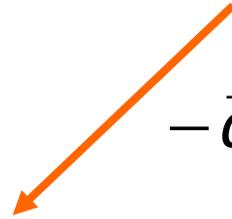
Multiplikation mit Skalar:



$\vec{a}$



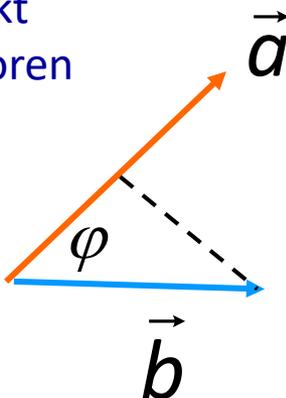
$0.6 \cdot \vec{a}$



$-\vec{a} = (-1) \cdot \vec{a}$

$$s \cdot \vec{a} = \begin{pmatrix} sa_x \\ sa_y \\ sa_z \end{pmatrix}$$

Skalarprodukt  
zweier Vektoren



$$\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y + a_z b_z$$

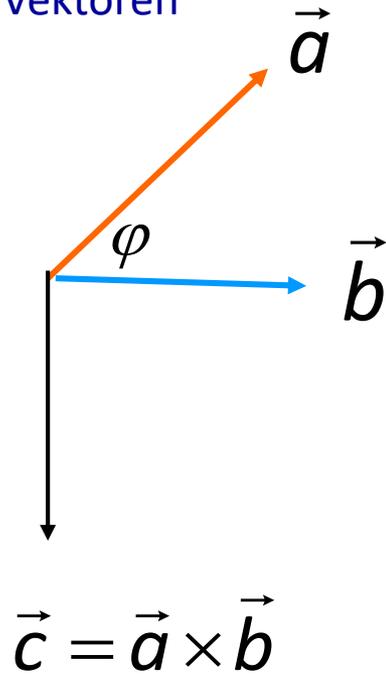
$$\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \varphi$$

$$|\vec{a}| = \sqrt{\vec{a} \cdot \vec{a}} \quad \text{Pythagoras}$$

$$\vec{a} \cdot \vec{b} = 0 \Leftrightarrow \vec{a} \perp \vec{b}$$

# Vektoren

Kreuzprodukt  
zweier Vektoren



$$\vec{c} \perp \vec{a} \text{ und } \vec{c} \perp \vec{b}$$

$$\vec{a} \times \vec{b} = \begin{pmatrix} a_y b_z - a_z b_y \\ a_z b_x - a_x b_z \\ a_x b_y - a_y b_x \end{pmatrix}$$

$$\vec{a} \times \vec{a} = 0$$

$$\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$$

$$|\vec{c}| = |\vec{a}| |\vec{b}| \sin \varphi$$

wenn  $a$  und  $b$   
senkrecht zueinander

$$|\vec{c}| = |\vec{a}| |\vec{b}|$$

# Gradient, Divergenz, Rotation

$$\vec{\nabla} = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix}$$

Nabla-Operator

Skalar

$$\vec{\nabla} \Phi = \text{grad } \Phi = \begin{pmatrix} \frac{\partial \Phi}{\partial x} \\ \frac{\partial \Phi}{\partial y} \\ \frac{\partial \Phi}{\partial z} \end{pmatrix}$$

Gradient

Skalar

$$\vec{\nabla}^2 \Phi = \Delta \Phi = \frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial^2 \Phi}{\partial y^2} + \frac{\partial^2 \Phi}{\partial z^2}$$

Laplace

Vektor

$$\vec{\nabla} \cdot \vec{u} = \text{div } \vec{u} = \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z}$$

Divergenz

Vektor

$$\vec{\nabla} \times \vec{u} = \text{rot } \vec{u} = \begin{pmatrix} \frac{\partial u_z}{\partial y} - \frac{\partial u_y}{\partial z} \\ \frac{\partial u_x}{\partial z} - \frac{\partial u_z}{\partial x} \\ \frac{\partial u_y}{\partial x} - \frac{\partial u_x}{\partial y} \end{pmatrix}$$

Rotation